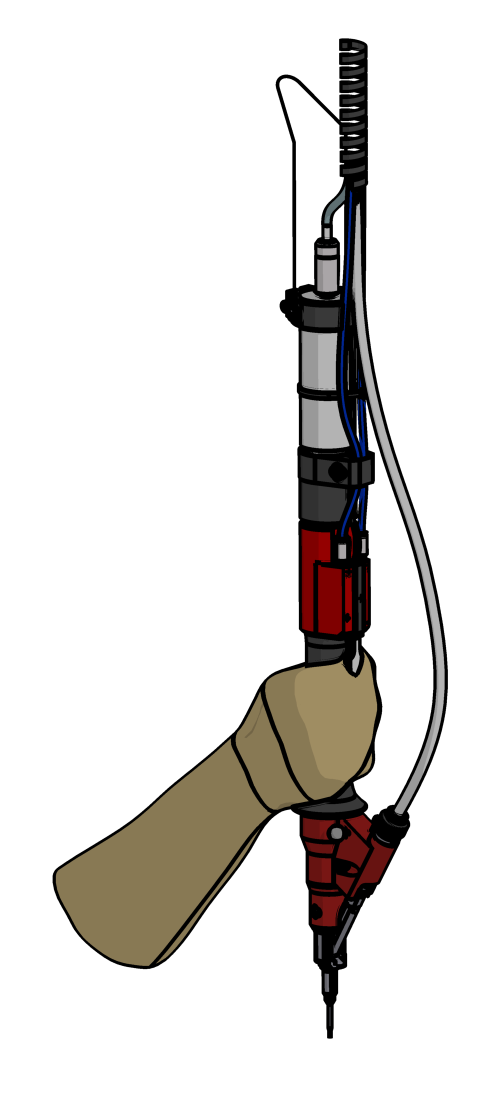
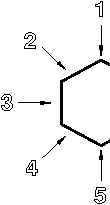
1. **Type of Quotation**
2. **RFQ Reference No.**
   1. Project Name
   2. Final Customer
   3. Country Final Customer
   4. Machine Tool Builder
3. **Reference System  
   3.1 - 3.4**Type of Drive and Controller
4. **Specification (Work Direction)**
5. **Drawings Attached(as required)**
6. **System Mounted on**
7. **Type of System and Amount**
8. **Controller requirement**
9. **Options**
10. **Additional Information**

|  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **No** | **Description** | **Shall be filled in by the customer** | | | | | | | | | |
| **1** | **Type of Quotation:** | **Rough Budget Price** | | | **Budget Price Quote** | | **Official Quotation** | | | | |
|  | | |  | |  | | | | |
| **2** | **RFQ Reference No.** |  | | | | | | | | | |
| **2.1** | **Project Name:** |  | | | | | | | | | |
| **2.2** | **Final Customer:** |  | | | | | | | | | |
| **2.3** | **Country Final Customer:** |  | | | | | | | | | |
| **2.4** | **Machine Tool Builder:** |  | | | | | | | | | |
| **3** | **Reference-System:** | **Copyof Machine:** | | | **Spare Parts for Machine:** | | **Modification of Machine:** | | | | |
|  | | |  | |  | | | | |
| **3.1** | **Type of drive and drive controller:** | **By ELMECH** | | | **By Customer** | | **Brand & Type (completename)** | | | | |
| **3.2** | **Electric** |  | | |  | |  | | | | |
| **3.3** | **Pneumatic** |  | | |  | |  | | | | |
| **3.4** | **+ Torque transducer** |  | | |  | |  | | | | |
| **4** | **Specification:** | **Torque +/- tolerance (Nm)** | | | **Working direction (1-5)** | | **Cycle time in Sec. (Start – home pos.)** | | | **Length of required stroke** | |
|  | | |  | |  | | |  | |
| **5** | **Drawings attached: in the way they shall be used** | **2D – screw drawing (metrical)** | | | **3D – file of part (.step)** | | **Tightening mask** | | | **Clamping device** | |
|  | | |  | |  | | |  | |
| **Scopeof Supply (preferred)** | | | | | | | | | | | |
| **6** | **System mounted on:** | **Axis System** | | | **Robot max. weight** | | **Stationary** | | | **Handling device** | |
| **XY** | | **XYZ** |  | **kg** |  | | |  | |
| **7** | **Type of System: (n=amount)** | **n** | **Screw drivingunit** | | **n** | **Feed unit** | | | **n** | **Control unit** |
|  |  | |  |  | | |  |  |
| **8** | **Interface between Controller and Master** | **Digital I/O** | | | **BUS systems (Profinet / Ethercat / etc.)** | | | | | |
|  | | |  | | | | | | |
| **9** | **Options:** | **Hopper** | | | **Spare parts** | | | **Manual  (foreignlanguage)** | | | |
|  | | |  | | |  | | | |
| **10** | **Additional Information:** | | | | | | | | | | |

**RFQ-phase:**

* This document has to be filled in for each request – this shall not be used for alternative solutions.
* Prices for packing, insurance and transport are not included unless otherwise specified.
* In case of an exact copy of existing machine, the ELMECH price will be reduced by - 5%.   
  Definition - Copy of machine: same screw, same customer parts, same application, same scope of supply

**Project-phase:**

* Design Approval (DAP) to ELMECH should be given within 5 workings days to ELMECH. If not, shipment date could be postponed depending on current capacity situation.
* If customer wants a change after the design has been approved, an additional quotation will be made and the customer must modify his order accordingly.  
  This may result in a higher price and additionally, we will have to ask for a handling fee for administrative efforts.